

RTA-OS

NXP i.MXRT with the Green Hills Compiler

Port Data Sheet

RTA-OS is the ETAS Classic AUTOSAR OS implementation. RTA-OS supports a wide variety of microcontroller/compiler combinations (RTA-OS ports). This port data sheet describes the support for the NXP i.MXRT with the Green Hills compiler

Supported Devices

RTA-OS supports the Cortex-M7 cores on the following variants of the NXP i.MXRT microcontrollers:

- iMXRT1010
- iMXRT1170

Toolchain support

This port supports the following compilers:

- Green Hills v2019.1.4

Interrupt model

On the iMXRT/GHS port, RTA-OS supports 15 levels of Category 1 and Category 2 ISRs, plus two fixed interrupts (HardFault and NMI) and user level.

Memory model

On the iMXRT/GHS port, RTA-OS uses the standard flat memory model, following standard EABI.

Memory overhead of RTA-OS

Object	RAM (bytes)	ROM (bytes)
Task	0	20
Cat 2 ISR	0	8
Resource	4	8
Alarm	12	2
Counter	4	20
Schedule Table	16	16
Expiry Point	0	4

Performance

The following gives the key RTA-OS kernel performance data measured in CPU cycles.

Action	Exec time	Ref
Pre-emption	79	A
Normal Termination	42	B
Task Switch	56	C
ChainTask	126	D
WaitEvent	242	E
SetEvent	288	F
Schedule	74	G
ReleaseResource	69	H
Cat 2 ISR Entry Latency	113	I
Cat 2 ISR Exit Latency – interrupted task	107	J
Cat 2 ISR Exit Latency – task switch	85	K
Cat 1 ISR Latency	37	L

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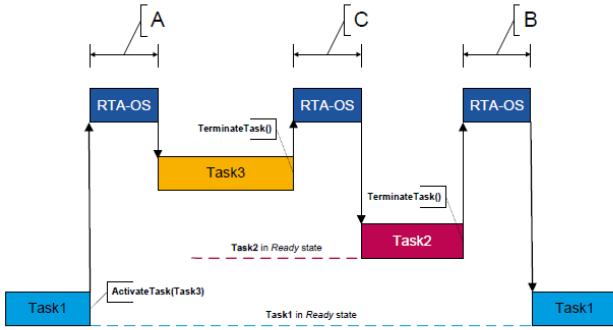


Figure 1 - Task1 is preempted by Task3, followed by a task switch and then normal termination of Task2

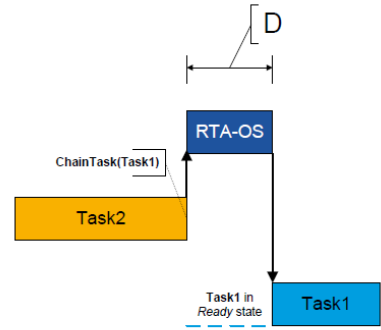


Figure 2 - Task2 chains Task1

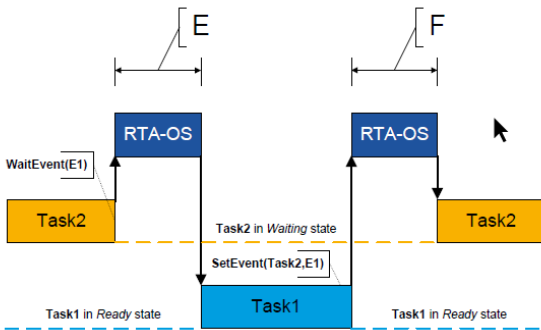


Figure 3 - Task2 waits for an event set by Task1

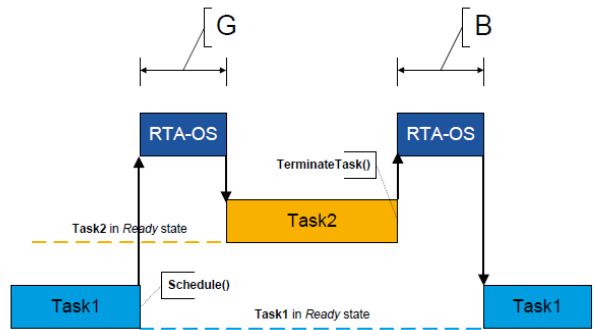


Figure 4 - Task1 allows cooperative scheduling by Task2

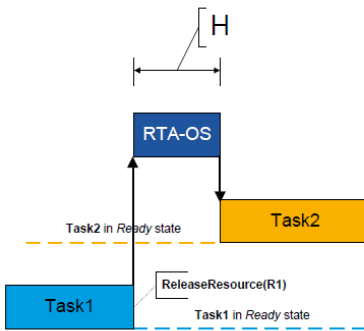


Figure 5 - Task1 releases a resource

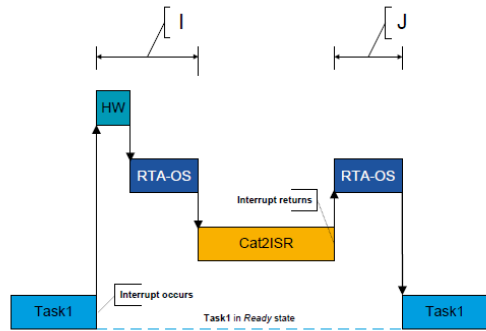


Figure 6 - Category2 ISR entry and exit latency

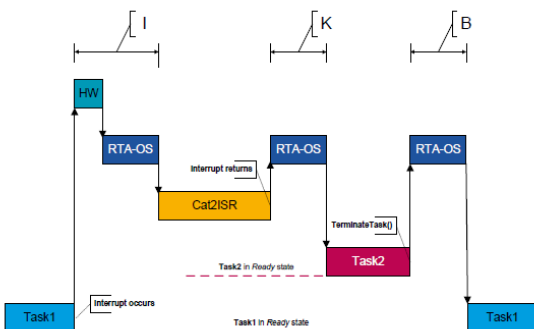


Figure 7 - Category2 ISR switches to Task2

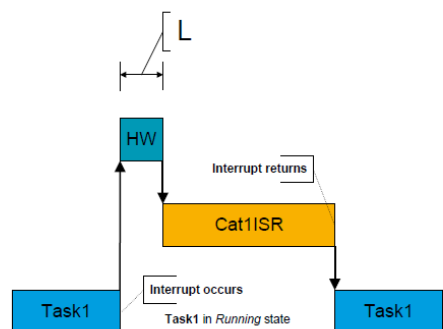


Figure 8 - Category1 ISR entry latency